Package: geodl (via r-universe)

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Type Package

Title Geospatial Semantic Segmentation with Torch and Terra

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Description Provides tools for semantic segmentation of geospatial data using convolutional neural network-based deep learning. Utility functions allow for creating masks, image chips, data frames listing image chips in a directory, and DataSets for use within DataLoaders. Additional functions are provided to serve as checks during the data preparation and training process. A UNet architecture can be defined with 4 blocks in the encoder, a bottleneck block, and 4 blocks in the decoder. The UNet can accept a variable number of input channels, and the user can define the number of feature maps produced in each encoder and decoder block and the bottleneck. Users can also choose to (1) replace all rectified linear unit (ReLU) activation functions with leaky ReLU or swish, (2) implement attention gates along the skip connections, (3) implement squeeze and excitation modules within the encoder blocks, (4) add residual connections within all blocks, (5) replace the bottleneck with a modified atrous spatial pyramid pooling (ASPP) module, and/or (6) implement deep supervision using predictions generated at each stage in the decoder. A unified focal loss framework is implemented after Yeung et al. (2022) <<https://doi.org/10.1016/j.compmedimag.2021.102026>>. We have also implemented assessment metrics using the 'luz' package including F1-score, recall, and precision. Trained models can be used to predict to spatial data without the need to generate

chips from larger spatial extents. Functions are available for performing accuracy assessment. The package relies on 'torch' for implementing deep learning, which does not require the installation of a 'Python' environment. Raster geospatial data are handled with 'terra'. Models can be trained using a Compute Unified Device Architecture (CUDA)-enabled graphics processing unit (GPU); however, multi-GPU training is not supported by 'torch' in 'R'.

```
Depends R (>= 4.1)
```
Imports torch ($>= 0.11.0$), torchvision ($>= 0.5.1$), dplyr ($>= 1.1.3$), terra (>= 1.7.55), luz (>= 0.4.0), MultiscaleDTM (>= 0.8.2), psych (>= 2.3.3), coro (>= 1.0.3), R6 (>= 2.5.1), readr (>= 2.1.3), rlang ($> = 1.1.1$)

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URL <https://github.com/maxwell-geospatial/geodl>,

<https://doi.org/10.31223/X53M6T>,

<https://www.wvview.org/geodl/index.html>

BugReports <https://github.com/maxwell-geospatial/geodl/issues>

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assessDL *assessDL*

Description

Assess semantic segmentation model using all samples in a torch DataLoader.

Usage

```
assessDL(
  dl,
  model,
  multiclass = TRUE,
  batchSize,
  size,
  nCls,
  cCodes,
  cNames,
  usedDS = FALSE,
  useCUDA = FALSE,
  decimals = 4
\mathcal{L}
```


Details

This function generates a set of summary assessment metrics based on all samples within a torch data loader. Results are returned as a list object. For multiclass assessment, the class names (\$Classes), count of samples per class in the reference data (\$referenceCounts), count of samples per class in the predictions (\$predictionCounts), confusion matrix (\$confusionMatrix), aggregated assessment metrics (SaggMetrics) (OA = overall accuracy, macroF1 = macro-averaged class aggregated F1-score, macroPA = macro-averaged class aggregated producer's accuracy or recall, and macroUA = macro-averaged class aggregated user's accuracy or precision), class-level user's accuracies or precisions (\$userAccuracies), class-level producer's accuracies or recalls (\$producerAccuracies), and class-level F1-scores (\$F1Scores). For a binary case, the \$Classes, \$referenceCounts, \$predictionCounts, and \$confusionMatrix objects are also returned; however, the \$aggMets object is replaced with \$Mets, which stores the following metrics: overall accuracy, recall, precision, specificity, negative predictive value (NPV), and F1-score. For binary cases, the second class is assumed to be the positive case.

Value

List object containing the resulting metrics and ancillary information.

Examples

```
## Not run:
metricsOut <- assessDL(dl=testDL,
                        model=model,
                        batchSize=15,
                        size=256,
                        nCls=2,
                        mode="binary",
                        c\text{Codes=c}(1,2),
                        cNames=c("Not Mine", "Mine"),
                        usedDS=FALSE,
                        useCUDA=TRUE,
                        decimals=4)
```
End(Not run)

assessPnts *assessPnts*

Description

Assess semantic segmentation model using point locations

Usage

```
assessPnts(
  reference,
 predicted,
 multiclass = TRUE,
 mappings = levels(as.factor(reference)),
  decimals = 4)
```
Arguments

Details

This function generates a set of summary assessment metrics when provided reference and predicted classes. Results are returned as a list object. For multiclass assessment, the class names (\$Classes), count of samples per class in the reference data (\$referenceCounts), count of samples per class in the predictions (\$predictionCounts), confusion matrix (\$confusionMatrix), aggregated assessment metrics (\$aggMetrics) ($OA = overall accuracy$, macro $F1 = macro-averaged class aggregated F1$ score, macroPA = macro-averaged class aggregated producer's accuracy or recall, amd macroUA = macro-averaged class aggregated user's accuracy or precision), class-level user's accuracies or precisions (\$userAccuracies), class-level producer's accuracies or recalls (\$producerAccuracies), and class-level F1-scores (\$F1Scores). For a binary case, the \$Classes, \$referenceCounts, \$prediction-Counts, and \$confusionMatrix objects are also returned; however, the \$aggMets object is replaced with \$Mets, which stores the following metrics: overall accuracy, recall, precision, specificity, negative predictive value (NPV), and F1-score. For binary cases, the second class is assumed to be the positive case.

Value

List object containing the resulting metrics and ancillary information.

Examples

```
#Multiclass example
```

```
#Generate example data as data frame of class predictions
inDF <- data.frame(ref = sample(c("Class A", "Class B", "Class C"), 1000, replace=TRUE),
pred = sample(c("Class A", "Class B", "Class C"), 1000, replace=TRUE))
#Calculate metrics
metsOut <- assessPnts(reference=inDF$ref,
                     predicted=inDF$pred,
                     multiclass=TRUE,
                     mappings = c("Class A", "Class B", "Class C"),
                     decimals=4)
print(metsOut)
#Binary example
#Generate example data as data frame of class predictions
inDF <- data.frame(ref = sample(c("Background", "Positive"), 1000, replace=TRUE),
                  pred = sample(c("Background", "Positive"), 1000, replace=TRUE))
#Calculate metrics
metsOut <- assessPnts(reference=inDF$ref,
                     predicted=inDF$pred,
                     multiclass=FALSE,
                     mappings = c("Background", "Positive"),
                     decimals=4)
print(metsOut)
```
assessRaster *assessRaster*

Description

Assess semantic segmentation model using categorical raster grids (wall-to-wall reference data and predictions)

Usage

```
assessRaster(
  reference,
  predicted,
  multiclass = TRUE,
```
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```
mappings = levels(as.factor(reference)),
 decimals = 4)
```
Arguments

Details

This function generates a set of summary assessment metrics when provided reference and predicted classes. Results are returned as a list object. For multiclass assessment, the class names (\$Classes), count of samples per class in the reference data (\$referenceCounts), count of samples per class in the predictions (\$predictionCounts), confusion matrix (\$confusionMatrix), aggregated assessment metrics (\$aggMetrics) ($OA = overall$ accuracy, macro $F1 =$ macro-averaged class aggregated $F1$ score, macroPA = macro-averaged class aggregated producer's accuracy or recall, and macroUA = macro-averaged class aggregated user's accuracy or precision), class-level user's accuracies or precisions (\$userAccuracies), class-level producer's accuracies or recalls (\$producerAccuracies), and class-level F1-scores (\$F1Scores). For a binary case, the \$Classes, \$referenceCounts, \$prediction-Counts, and \$confusionMatrix objects are also returned; however, the \$aggMets object is replaced with \$Mets, which stores the following metrics: overall accuracy, recall, precision, specificity, negative predictive value (NPV), and F1-score. For binary cases, the second class is assumed to be the positive case.

Value

List object containing the resulting metrics and ancillary information.

Examples

```
if(requireNamespace("terra", quietly = TRUE)){
require(torch)
require(terra)
#Multiclass example
#Generate example data as SpatRasters
ref <- terra::rast(matrix(sample(c(1, 2, 3), 625, replace=TRUE), nrow=25, ncol=25))
pred <- terra::rast(matrix(sample(c(1, 2, 3), 625, replace=TRUE), nrow=25, ncol=25))
```

```
#Calculate metrics
metsOut <- assessRaster(reference=ref,
                        predicted=pred,
                        multiclass=TRUE,
                        mappings=c("Class A", "Class B", "Class C"),
                        decimals=4)
print(metsOut)
#Binary example
#Generate example data as SpatRasters
ref <- terra::rast(matrix(sample(c(0, 1), 625, replace=TRUE), nrow=25, ncol=25))
pred <- terra::rast(matrix(sample(c(0, 1), 625, replace=TRUE), nrow=25, ncol=25))
#Calculate metrics
metsOut <- assessRaster(reference=ref,
                        predicted=pred,
                        multiclass=FALSE,
                        mappings=c("Background", "Positive"),
                        decimals=4)
print(metsOut)
}
```

```
defineMobileUNet defineMobileUNet
```
Description

Define a UNet architecture for geospatial semantic segmentation with a MobileNet-v2 backbone.

Usage

```
defineMobileUNet(
 nCls = 3,
 pretrainedEncoder = TRUE,
 freezeEncoder = TRUE,
 actFunc = "relu",useAttn = FALSE,useDS = FALSE,dcChn = c(256, 128, 64, 32, 16),
 negative_slope = 0.01
)
```
Arguments

nCls Number of classes being differentiated. For a binary classification, this can be either 1 or 2. If 2, the problem is treated as a multiclass problem, and a multiclass loss metric should be used. Default is 3.

pretrainedEncoder

Details

Define a UNet architecture with a MobileNet-v2 backbone or encoder. This UNet implementation was inspired by a blog post by Sigrid Keydana available [here.](https://blogs.rstudio.com/ai/posts/2021-10-29-segmentation-torch-android/) This architecture has 6 blocks in the encoder (including the bottleneck) and 5 blocks in the decoder. The user is able to implement deep supervision (use $DS = TRUE$) and attention gates along the skip connections (useAttn = TRUE). This model requires three input bands or channels.

Value

ModileUNet model instance as torch nn_module

Examples

```
require(torch)
#Generate example data as torch tensor
tensorIn <- torch::torch_rand(c(12,3,128,128))
#Instantiate model
model <- defineMobileUNet(nCls = 3,
                          pretrainedEncoder = FALSE,
                          freezeEncoder = FALSE,
                          actFunc = "relu",
                          useAttn = TRUE,
                          useDS = TRUE,
                          dcChn = c(256,128,64,32,16),
                          negative\_slope = 0.01
```
pred <- model(tensorIn)

defineSegDataSet *defineSegDataSet*

Description

Instantiate a subclass of torch::dataset() for geospatial semantic segmentation

Usage

```
defineSegDataSet(
  chpDF,
  folder,
  normalize = FALSE,
  rescaleFactor = 1,
 mskRescale = 1,
 mskAdd = 0,bands = c(1, 2, 3),
 bMns = 1,
 bSDs = 1,
  doAugs = FALSE,
 maxAugs = 0,
 probVFlip = 0,
 probHFlip = 0,
 probBrightness = 0,
 probContrast = 0,
 probGamma = 0,
 probHue = 0,
 probSaturation = 0,
 brightFactor = c(0.8, 1.2),
  contrastFactor = c(0.8, 1.2),
  gammaFactor = c(0.8, 1.2, 1),
 hueFactor = c(-0.2, 0.2),
  saturationFactor = c(0.8, 1.2))
```


negative number. For example, 0 gives a solid gray image, 1 gives the original image, and 2 increases the contrast by a factor of 2.

- gammaFactor Vector of smallest and largest gamma values and gain value for a total of 3 values. Random value will be selected between these extremes. The default gamma value range is 0.8 to 1.2 and the default gain is 1. The gain is not randomly altered, only the gamma. Non negative real number. A gamma larger than 1 makes the shadows darker while a gamma smaller than 1 makes dark regions lighter.
- hueFactor Vector of smallest and largest hue adjustment factors. Random value will be selected between these extremes. The default is -0.2 to 0.2. Should be in range -0.5 to 0.5. 0.5 and -0.5 give complete reversal of hue channel in HSV space in positive and negative direction, respectively. 0 means no shift. Therefore, both -0.5 and 0.5 will give an image with complementary colors while 0 gives the original image.

saturationFactor

Vector of smallest and largest saturation adjustment factors. Random value will be selected between these extremes. The default is 0.8 to 1.2. For example, 0 will give a black-and-white image, 1 will give the original image, and 2 will enhance the saturation by a factor of 2.

Details

This function instantiates a subclass of torch::dataset() that loads data generated using the makeChips() or makeChipsMultiClass() function. Can also define random augmentations to combat overfitting. Note that horizontal and vertical flips will affect the alignment of the image and associated mask chips. As a result, the same augmentation will be applied to both the image and the mask. Changes in brightness, contrast, gamma, hue, and saturation will not be applied to the masks since alignment is not impacted by these transformations. Predictor variables are generated with three dimensions (channel/variable, width, height) regardless of the number of channels/variables. Masks are generated as three dimensional tensors (class index, width, height).

Value

A dataset object that can be provided to torch::dataloader().

Examples

```
## Not run:
#Define training dataset and augmentations
trainDS <- defineSegDataSet(
 chpDF=trainDF,
 folder="PATH TO CHIPS FOLDER",
 normalize = FALSE,
 rescaleFactor = 255,
 mskRescale= 255,
 bands = c(1, 2, 3),mskAdd=1,
 doAugs = TRUE,maxAugs = 1,
```
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```
probVFlip = .5,
probHFlip = .5,
probBrightness = 0,
probContrast = 0,
probGamma = 0,
probHue = 0,
probSaturation = 0,
brightFactor = c(.9,1.1),
contrastFactor = c(.9,1.1),gammaFactor = c(.9, 1.1, 1),hueFactor = c(-.1, .1),
saturationFactor = c(.9, 1.1))
```
End(Not run)

defineUNet *defineUNet*

Description

Define a UNet architecture for geospatial semantic segmentation.

Usage

```
defineUNet(
  inChn = 3,
  nCls = 3,
  actFunc = "relu",
  useAttn = FALSE,useSE = FALSE,
  useRes = FALSE,
  useASPP = FALSE,
  useDS = FALSE,
  enChn = c(16, 32, 64, 128),
  dcChn = c(128, 64, 32, 16),
 btnChn = 256,
  dilRates = c(1, 2, 4, 8, 16),
  dilChn = c(16, 16, 16, 16, 16),
  negative\_slope = 0.01,seRatio = 8
)
```


Details

Define a UNet architecture with 4 blocks in the encoder, a bottleneck block, and 4 blocks in the decoder. UNet can accept a variable number of input channels, and the user can define the number of feature maps produced in each encoder and decoder block and the bottleneck. Users can also choose to (1) replace all ReLU activation functions with leaky ReLU or swish, (2) implement attention gates along the skip connections, (3) implement squeeze and excitation modules within the encoder blocks, (4) add residual connections within all blocks, (5) replace the bottleneck with a modified atrous spatial pyramid pooling (ASPP) module, and/or (6) implement deep supervision using predictions generated at each stage in the decoder.

Value

Unet model instance as torch nnn_module

defineUnifiedFocalLoss 15

Examples

```
require(torch)
# example code
#Generate example data as torch tensor
tensorIn <- torch::torch_rand(c(12,4,128,128))
#Instantiate model
model <- defineUNet(inChn = 4,
                    nCls = 3,
                    actFunc = "lrelu",useAttn = TRUE,useSE = TRUE,
                    useRes = TRUE,
                    useASPP = TRUE,
                    useDS = TRUE,
                    enChn = c(16, 32, 64, 128),
                    dcChn = c(128, 64, 32, 16),
                    btnChn = 256,
                    dilRates=c(1,2,4,8,16),
                    dilChn=c(16,16,16,16,16),
                    negative_slope = 0.01,
                    seRatio=8)
 #Predict data with model
pred <- model(tensorIn)
```
defineUnifiedFocalLoss

defineUnifiedFocalLoss

Description

Define a loss for semantic segmentation using a modified unified focal loss framework as a subclass of torch::nn_module()

Usage

```
defineUnifiedFocalLoss(
  nCls = 3,
  lambda = 0.5,
  gamma = 0.5,
  delta = 0.6,
  smooth = 1e-08,zeroStart = TRUE,
  clsWghtsDist = 1,
  clsWghtsReg = 1,
  useLogCosH = FALSE,
  device = "cuda"
)
```
Arguments

Details

Implementation of modified version of the unified focal loss after:

Yeung, M., Sala, E., Schönlieb, C.B. and Rundo, L., 2022. Unified focal loss: Generalising Dice and cross entropy-based losses to handle class imbalanced medical image segmentation. Computerized Medical Imaging and Graphics, 95, p.102026.

Modifications include (1) allowing users to define class weights for both the distribution- based and region-based losses, (2) using class weights as opposed to the symmetric and asymmetric methods implemented by the authors, and (3) including an option to apply a logcosh transform to the regionbased loss.

This loss has three key hyperparameters that control its implementation. Lambda controls the relative weight of the distribution- and region-based losses. Default is 0.5, or equal weighting between the losses is applied. If lambda $= 1$, only the distribution- based loss is considered. If lambda $= 0$, only the region-based loss is considered. Values between 0.5 and 1 put more weight on the distribution-based loss while values between 0 and 0.5 put more weight on the region-based loss.

Gamma controls the application of focal loss and the application of increased weight to difficultto-predict pixels (for distribution-based losses) or difficult-to-predict classes (region-based losses). Lower gamma values put increased weight on difficult samples or classes. Using a value of 1 equates to not using a focal adjustment.

The delta term controls the relative weight of false positive and false negative errors for each class. The default is 0.6 for each class, which results in placing a higher weight on false negative as opposed to false positive errors relative to that class.

By adjusting the lambda, gamma, delta, and class weight terms, the user can implement a variety of different loss metrics including cross entropy loss, weighted cross entropy loss, focal cross entropy loss, focal weighted cross entropy loss, Dice loss, focal Dice loss, Tversky loss, and focal Tversky loss.

Value

Loss metric for use in training process.

Examples

```
library(terra)
library(torch)
#Generate example data as SpatRasters
ref <- terra::rast(matrix(sample(c(1, 2, 3), 625, replace=TRUE), nrow=25, ncol=25))
pred1 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred2 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred3 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred <- c(pred2, pred2, pred3)
#Convert SpatRaster to array
ref <- terra::as.array(ref)
pred <- terra::as.array(pred)
#Convert arrays to tensors and reshape
ref <- torch::torch_tensor(ref, dtype=torch::torch_long())
pred <- torch::torch_tensor(pred, dtype=torch::torch_float32())
ref <- ref$permute(c(3,1,2))
pred <- pred$permute(c(3,1,2))
#Add mini-batch dimension
ref <- ref$unsqueeze(1)
pred <- pred$unsqueeze(1)
#Duplicate tensors to have a batch of two
ref <- torch::torch_cat(list(ref, ref), dim=1)
pred <- torch::torch_cat(list(pred, pred), dim=1)
#Instantiate loss metric
myDiceLoss <- defineUnifiedFocalLoss(nCls=3,
                                    lambda=0, #Only use region-based loss
                                    gamma= 1,
                                    delta= 0.5, #Equal weights for FP and FN
                                    smooth = 1e-8,
```

```
zeroStart=FALSE,
clsWghtsDist=1,
clsWghtsReg=1,
useLogCosH =FALSE,
device='cpu')
```
#Calculate loss myDiceLoss(pred, ref)

defineUnifiedFocalLossDS

defineUnifiedFocalLossDS

Description

Define a loss for geospatial semantic segmentation using a modified unified focal loss framework as a subclass of torch::nn_module() when using deep supervision.

Usage

```
defineUnifiedFocalLossDS(
  nCls = 3,
  dsWghts = c(0.6, 0.2, 0.1, 0.1),
  lambda = 0.5,
  gamma = 0.5,
  delta = 0.6,
  smooth = 1e-08,
  zeroStart = TRUE,
  clsWghtsDist = 1,
  clsWghtsReg = 1,
  useLogCosH = FALSE,
  device = "cuda"
)
```


Details

Implementation of modified version of the unified focal loss after:

Yeung, M., Sala, E., Schönlieb, C.B. and Rundo, L., 2022. Unified focal loss: Generalising Dice and cross entropy-based losses to handle class imbalanced medical image segmentation. Computerized Medical Imaging and Graphics, 95, p.102026.

Modifications include (1) allowing users to define class weights for both the distribution- based and region-based losses, (2) using class weights as opposed to the symmetric and asymmetric methods implemented by the authors, and (3) including an option to apply a logcosh transform to the regionbased loss.

This loss has three key hyperparameters that control its implementation. Lambda controls the relative weight of the distribution- and region-based losses. Default is 0.5, or equal weighting between the losses is applied. If lambda $= 1$, only the distribution- based loss is considered. If lambda = 0, only the region-based loss is considered. Values between 0.5 and 1 put more weight on the distribution-based loss while values between 0 and 0.5 put more weight on the region-based loss.

Gamma controls the application of focal loss and the application of increased weight to difficultto-predict pixels (for distribution-based losses) or difficult-to-predict classes (region-based losses). Lower gamma values put increased weight on difficult samples or classes. Using a value of 1 equates to not using a focal adjustment.

The delta term controls the relative weight of false positive and false negative errors for each class. The default is 0.6 for each class, which results in placing a higher weight on false negative as opposed to false positive errors relative to that class.

By adjusting the lambda, gamma, delta, and class weight terms, the user can implement a variety of different loss metrics including cross entropy loss, weighted cross entropy loss, focal cross entropy loss, focal weighted cross entropy loss, Dice loss, focal Dice loss, Tversky loss, and focal Tversky loss.

Value

Loss metric for use in training process.

describeBatch *describeBatch*

Description

Generate summary information for a batch of image chips and masks.

Usage

```
describeBatch(dataLoader, zeroStart = FALSE)
```
Arguments

Details

The goal of this function is to provide a check of a mini-batch of image chips and associated masks generated by a DataLoader instance using defineSegDataSet(). Summary information includes the mini-batch size (batchSize); image chip data type (imageDataType); mask data type (mask-DataType); the shape of the mini-batch of images or predictor variables as mini-batch size, number of channels, width pixel count, and height pixel count (imageShape); the mask shape (maskShape); image band means (bndMns); image band standard deviations (bndSDs); count of pixels in each class in the mini-batch (maskCnts); and minimum (minIndex) and maximum (maxIndex) class indices present in the mini-batch.

Value

List object summarizing a mini-batch of image chips and masks.

Examples

```
## Not run:
trainStats <- describeBatch(trainDL,
tzeroStart=TRUE,
tusedDS=FALSE)
```
End(Not run)

describeChips *describeChips*

Description

Generate data frame of band summary statistics and class pixel counts

Usage

```
describeChips(
 folder,
 extension = ".tif",
 mode = "All",subSample = TRUE,
 numChips = 200,
 numChipsBack = 200,
 subSamplePix = TRUE,
  sampsPerChip = 100
)
```


sampsPerChip If subSamplePix is TRUE, this parameters specifies the number of random pixels to sample per chip. The default is 100. If subSamplePix is set to FALSE, this parameter is ignored.

Details

This function generates a set of summary metrics from image chips and associated masks stored in a directory. For each band, the minimum, median, mean, maximum, and standard deviation are returned (along with some other metrics). For mask data, the count of pixels in each class are returned. These summarizations can be useful for data normalization and determining class weightings in loss calculations.

Value

List object containing the summary metrics for each band in the \$ImageStats object and the count of pixels by class in the \$maskStats object.

Examples

```
## Not run:
chpDescript <- describeChips(folder= "PATH TO CHIPS FOLDER",
                             extension = ".tif",
                             mode = "Positive",
                             subSample = TRUE,
                             numChips = 100.
                             numChipsBack = 100,
                             subSamplePix = TRUE,
                             sampsPerChip = 400)
## End(Not run)
```
luz_metric_f1score *luz_metric_f1score*

Description

luz_metric function to calculate the macro-averaged, class aggregated F1-score

Usage

```
luz_metric_f1score(
  nCls = 1,
  smooth = 1,
  mode = "multiclass",
  biThresh = 0.5,
  clswghts = rep(1, nCls),zeroStart = TRUE,
  usedDS = FALSE
)
```
Arguments

Details

Calculates F1-score based on luz_metric() for use within training and validation loops.

Value

Calculated metric returned as a base-R vector as opposed to tensor.

Examples

```
library(terra)
library(torch)
#Generate example data as SpatRasters
ref <- terra::rast(matrix(sample(c(1, 2, 3), 625, replace=TRUE), nrow=25, ncol=25))
pred1 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred2 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred3 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred <- c(pred2, pred2, pred3)
#Convert SpatRaster to array
ref <- terra::as.array(ref)
pred <- terra::as.array(pred)
#Convert arrays to tensors and reshape
ref <- torch::torch_tensor(ref, dtype=torch::torch_long())
pred <- torch::torch_tensor(pred, dtype=torch::torch_float32())
ref \leq ref$permute(c(3,1,2))
pred <- pred$permute(c(3,1,2))
```

```
#Add mini-batch dimension
ref <- ref$unsqueeze(1)
pred <- pred$unsqueeze(1)
#Duplicate tensors to have a batch of two
ref <- torch::torch_cat(list(ref, ref), dim=1)
pred <- torch::torch_cat(list(pred, pred), dim=1)
#Calculate Macro-Averaged, Class Aggregated F1-Score
metric<-luz_metric_f1score(nCls=3,
                           smooth=1e-8,
                           mode = "multiclass",
                           zeroStart=FALSE,
                           usedDS=FALSE)
metric<-metric$new()
metric$update(pred,ref)
metric$compute()
```
luz_metric_overall_accuracy

luz_metric_overall_accuracy

Description

luz_metric function to calculate overall accuracy ((correct/total)*100)

Usage

```
luz_metric_overall_accuracy(
 nCls = 1,
  smooth = 1,
 mode = "multiclass",
 biThresh = 0.5,
  zeroStart = TRUE,
  usedDS = FALSE
```
)

Value

Calculated metric returned as a base-R vector as opposed to tensor.

Examples

```
require(terra)
require(torch)
#Generate example data as SpatRasters
ref <- terra::rast(matrix(sample(c(1, 2, 3), 625, replace=TRUE), nrow=25, ncol=25))
pred1 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred2 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred3 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred <- c(pred2, pred2, pred3)
#Convert SpatRaster to array
ref <- terra::as.array(ref)
pred <- terra::as.array(pred)
#Convert arrays to tensors and reshape
ref <- torch::torch_tensor(ref, dtype=torch::torch_long())
pred <- torch::torch_tensor(pred, dtype=torch::torch_float32())
ref \leq ref$permute(c(3,1,2))
pred <- pred$permute(c(3,1,2))
#Add mini-batch dimension
ref <- ref$unsqueeze(1)
pred <- pred$unsqueeze(1)
#Duplicate tensors to have a batch of two
ref <- torch::torch_cat(list(ref, ref), dim=1)
pred <- torch::torch_cat(list(pred, pred), dim=1)
#Calculate Overall Accuracy
metric<-luz_metric_overall_accuracy(nCls=3,
                                   smooth=1e-8,
                                   mode = "multiclass",
                                   zeroStart=FALSE,
                                   usedDS=FALSE)
metric<-metric$new()
metric$update(pred,ref)
metric$compute()
```
luz_metric_precision *luz_metric_precision*

Description

luz_metric function to calculate macro-averaged, class aggregated precision

Usage

```
luz_metric_precision(
 nCls = 3,smooth = 1,
 mode = "multiclass",
 biThresh = 0.5,
 zeroStart = TRUE,
 clsWghts = rep(1, nCls),
 usedDS = TRUE)
```
Arguments

Details

Calculates precision based on luz_metric() for use within training and validation loops.

Value

Calculated metric returned as a base-R vector as opposed to tensor.

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Examples

```
library(terra)
library(torch)
#Generate example data as SpatRasters
ref <- terra::rast(matrix(sample(c(1, 2, 3), 625, replace=TRUE), nrow=25, ncol=25))
pred1 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred2 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred3 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred <- c(pred2, pred2, pred3)
#Convert SpatRaster to array
ref <- terra::as.array(ref)
pred <- terra::as.array(pred)
#Convert arrays to tensors and reshape
ref <- torch::torch_tensor(ref, dtype=torch::torch_long())
pred <- torch::torch_tensor(pred, dtype=torch::torch_float32())
ref \leq ref$permute(c(3,1,2))
pred <- pred$permute(c(3,1,2))
#Add mini-batch dimension
ref <- ref$unsqueeze(1)
pred <- pred$unsqueeze(1)
#Duplicate tensors to have a batch of two
ref <- torch::torch_cat(list(ref, ref), dim=1)
pred <- torch::torch_cat(list(pred, pred), dim=1)
#Calculate Macro-Averaged, Class Aggregated Precision
metric<-luz_metric_precision(nCls=3,
                             smooth=1e-8,
                             mode = "multiclass",
                             zeroStart=FALSE,
                             usedDS=FALSE)
metric<-metric$new()
metric$update(pred,ref)
metric$compute()
```
luz_metric_recall *luz_metric_recall*

Description

luz_metric function to calculate macro-averaged, class aggregated recall

Usage

```
luz_metric_recall(
  nCls = 3,
```

```
smooth = 1,
 mode = "multiclass",
 biThresh = 0.5,
 zeroStart = TRUE,
 clsWghts = rep(1, nCls),usedDS = TRUE
)
```
Arguments

Details

Calculates recall based on luz_metric() for use within training and validation loops.

Value

Calculated metric returned as a base-R vector as opposed to tensor.

Examples

```
library(terra)
library(torch)
#Generate example data as SpatRasters
ref <- terra::rast(matrix(sample(c(1, 2, 3), 625, replace=TRUE), nrow=25, ncol=25))
pred1 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred2 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred3 <- terra::rast(matrix(sample(c(1:150), 625, replace=TRUE), nrow=25, ncol=25))
pred <- c(pred2, pred2, pred3)
```
#Convert SpatRaster to array

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```
ref <- terra::as.array(ref)
pred <- terra::as.array(pred)
#Convert arrays to tensors and reshape
ref <- torch::torch_tensor(ref, dtype=torch::torch_long())
pred <- torch::torch_tensor(pred, dtype=torch::torch_float32())
ref \leq ref$permute(c(3,1,2))
pred <- pred$permute(c(3,1,2))
#Add mini-batch dimension
ref <- ref$unsqueeze(1)
pred <- pred$unsqueeze(1)
#Duplicate tensors to have a batch of two
ref <- torch::torch_cat(list(ref, ref), dim=1)
pred <- torch::torch_cat(list(pred, pred), dim=1)
#Calculate Macro-Averaged, Class Aggregated Recall
metric<-luz_metric_recall(nCls=3,
                          smooth=1e-8,
                          mode = "multiclass",
                          zeroStart=FALSE,
                          usedDS=FALSE)
metric<-metric$new()
metric$update(pred,ref)
metric$compute()
```
makeChips *makeChips*

Description

Generate image chips from images and associated raster masks

Usage

```
makeChips(
  image,
  mask,
  n_channels = 3,
  size = 256,
  stride_x = 256,
  stride_y = 256,
  outDir,
 mode = "All",useExistingDir = FALSE
)
```
Arguments

Details

This function generates image and mask chips from an input image and associated raster mask. The chips are written into the defined directory. The number of rows and columns of pixels in each chip are equal to the size argument. If a stride_x and/or stride_y is used that is different from the size argument, resulting chips will either overlap or have gaps between them. In order to not have overlap or gaps, the stride_x and stride_y arguments should be the same as the size argument. Both the image chips and associated masks are written to TIFF format (".tif"). Input data are not limited to three band images. This function is specifically for a binary classification where the positive case is indicated with a cell value of 1 and the background or negative case is indicated with a cell value of 0. If an irregular shaped raster grid is provided, only chips and masks that contain no NA or NoDATA cells will be produced.

Three modes are available. If "All" is used, all image chips are generated even if they do not contain pixels mapped to the positive case. Within the provided directory, image chips will be written to an "images" folder and masks will be written to a "masks" folder. If "Positive" is used, only chips that have at least 1 pixel mapped to the positive class will be produced. Background- only chips will not be generated. Within the provided directory, image chips will be written to an "images" folder and masks will be written to a "masks" folder. Lastly, if the "Divided" method is used, separate "positive" and "background" folders will be created with "images" and "masks" subfolders. Any chip that has at least 1 pixel mapped to the positive class will be written to the "positive" folder while any chip having only background pixels will be written to the "background" folder.

Value

Image and mask files written to disk in TIFF format. No R object is returned.

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Examples

```
## Not run:
makeChips(image = "INPUT IMAGE FILE NAME AND PATH",
         mask = "INPUT RASTER MASK FILE NAME AND PATH",
          n_channels = 3,
          size = 256,
          stride_x = 256,
          stride_y = 256,
          outDir = "OUTPUT DIRECTY IN WHICH TO SAVE CHIPS",
          mode = "Positive",
          useExistingDir=FALSE)
```

```
## End(Not run)
```
makeChipsDF *makeChipsDF*

Description

Create data frame and CSV file listing image chips and associated masks

Usage

```
makeChipsDF(
 folder,
 outCSV,
 extension = ".tif",
 mode = "All",shuffle = FALSE,
 saveCSV = FALSE
)
```


Details

This function creates a data frame and, optionally, a CSV file that lists all of the image chips and associated masks in a directory. Three columns are produced. The chpN column provides the name of the chip, the chpPth column provides the path to the chip, and the chpMsk column provides the path to the associated mask. All paths are relative to the input folder as opposed to the full file path so that the results can still be used if the data are copied to a new location on disk or to a new computer.

Value

Data frame with three columns (chpN, chpPth, and mskPth) and, optionally, a CSV file written to disk. If mode = "Divided", a division column is added to differentiate "positive" and "background" samples.

Examples

```
## Not run:
chpDF <- makeChipsDF(folder = "PATHT TO CHIPS FOLDER",
                      outCSV = "OUTPUT CSV FILE AND PATH",
                      extension = ".tif",mode="Positive",
                      shuffle=TRUE,
                      saveCSV=TRUE)
```
End(Not run)

makeChipsMultiClass *makeChipsMultiClass*

Description

Generate image chips from images and associated raster masks for multiclass classification

Usage

```
makeChipsMultiClass(
  image,
  mask,
  n_channels = 3,
  size = 256,
```
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```
stride_x = 256,
stride_y = 256,
outDir,
useExistingDir = FALSE
```
Arguments

)

Details

This function generates image and mask chips from an input image and associated raster mask. The chips will be written into the defined directory. The number of rows and columns of pixels per chip are equal to the size argument. If a stride_x and/or stride_y is used that is different from the size argument, resulting chips will either overlap or have gaps between them. In order to not have overlap or gaps, the stride_x and stride_y arguments should be the same as the size argument. Both the image chips and associated masks are written to TIFF format (".tif"). Input data are not limited to three band images. This function is specifically for a multiclass classification. For a binary classification or when only two classes are differentiated, use the makeChips() function. If an irregular shaped raster grid is provided, only chips and masks that contain no NA or NoDATA cells will be produced.

Within the provided directory, image chips will be written to an "images" folder and masks will be written to a "masks" folder.

Value

Image and mask files written to disk in TIFF format. No R object is returned.

Examples

```
## Not run:
makeChipsMultiClass(image = "INPUT IMAGE NAME AND PATH",
                   mask = "INPUT RASTER MASK NAME AND PATH",
                    n_channels = 3,
                    size = 512,stride_x = 512,
                    stride_y = 512,
                    outDir = "DIRECTORY IN WHICH TO SAVE CHIPS",
                    useExistingDir=FALSE)
```
End(Not run)

makeMasks *makeMasks*

Description

Make raster mask from input vector data

Usage

```
makeMasks(
  image,
  features,
 crop = FALSE,
  extent,
  field,
 background = 0,
 outImage,
 outMask,
 mode = "Both"
)
```


Details

This function creates a raster mask from input vector data. The cell value is indicated by the field parameter. A unique numeric code should be provided for each class. In the case of a binary classification, 0 should indicate background and 1 should indicate positive. For a multiclass problem, values should be sequential from 0 to n-1, where n is the number of classes, or 1 to n. We recommend using 1 to n. If no cropping is applied, the generated raster mask will have the same spatial extent, number of rows of pixels, number of columns of pixels, cell size, and coordinate reference system as the input image.

Value

Single-band raster mask written to disk in TIFF format and, optionally, a copy of the image written to disk. Cropping may be applied as specified. No R objects are returned.

Examples

```
## Not run:
makeMasks(image = "INPUT IMAGE FILE AND PATH",
         features = "INPUT VECTOR FEATURES FILE AND PATH",
         crop = TRUE,extent = "INPUT VECTOR BOUNDARY and PATH",
         field = "ATTRIBUTE COLUMN NAME",
         background = 0,
```

```
outImage = "OUTPUT IMAGE NAME AND PATH",
outMask = "OUTPUT MASK NAME AND PATH",
mode = "Both")
```
End(Not run)

makeTerrainDerivatives

makeTerrainDerivatives

Description

Make three band terrain stack from input digital terrain model

Usage

makeTerrainDerivatives(dtm, res, filename)

Arguments

Details

This function creates a three-band raster stack from an input digital terrain model (DTM) of bare earth surface elevations. The first band is a topographic position index (TPI) calculated using a moving window with a 50 m circular radius. The second band is the square root of slope calculated in degrees. The third band is a TPI calculated using an annulus moving window with an inner radius of 2 and outer radius of 5 meters. The TPI values are clamped to a range of -10 to 10 then linearly rescaled from 0 and 1. The square root of slope is clamped to a range of 0 to 10 then linearly rescaled from 0 to 1. Values are provided in floating point.

The stack is described in the following publication and was originally proposed by William Odom of the United States Geological Survey (USGS):

Maxwell, A.E., W.E. Odom, C.M. Shobe, D.H. Doctor, M.S. Bester, and T. Ore, 2023. Exploring the influence of input feature space on CNN-based geomorphic feature extraction from digital terrain data, Earth and Space Science, 10: e2023EA002845. https://doi.org/10.1029/2023EA002845.

Value

Three-band raster grid written to disk in TIFF format and spatRaster object.

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Examples

```
## Not run:
inDTM <- terra::rast("INPUT DTM NAME AND PATH")
terrOut <- makeTerrainDerivatives(dtm=inDTM,
                                 res=2,
                                 filename="OUT TERRAIN STACK NAME AND PATH")
```
End(Not run)

predictSpatial *predictSpatial*

Description

Apply a trained semantic segmentation model to predict back to geospatial raster data

Usage

```
predictSpatial(
  imgIn,
 model,
 predOut,
 mode = "multiclass",
 predType = "class",
 biThresh = 0.5,
 useCUDA = FALSE,
 nCls,
 chpSize,
  stride_x,
  stride_y,
  crop,
  nChn = 3,
  normalize = FALSE,
  bMns,
 bSDs,
  rescaleFactor = 1,
 usedDS = FALSE
```
)

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Details

This function generates a pixel-by-pixel prediction using input data and a trained semantic segmentation model. Can return either hard classifications, logits, or rescaled logits with a sigmoid or softmax activation applied. Note that this package treats all problems as multiclass problems and does not differentiate between binary and multiclass classification. As a result, in our workflow the multiclass mode should be used. Result is written to disk and provided as a spatRaster object. If you are experiencing memory issues, you may need to break larger raster extents into smaller tiles for processing.

Value

A spatRast object and a raster grid saved to disk of predicted class indices (predType = "class"), logits (predType = "logit"), or rescaled logits (predType = "prob").

Examples

```
## Not run:
#Predict classification
predCls <- predictSpatial(imgIn="INPUT IMAGE NAME AND PATH",
                          model=model,
                          predOut="OUTPUT RASTER NAME AND PATH",
                          mode="multiclass",
                           predType="class",
                           useCUDA=TRUE,
                           nCls=2,
                           chpSize=256,
                           stride_x=128,
                           stride_y=128,
                           crop=50,
                           nChn=3,
                           normalize=FALSE,
                           rescaleFactor=255,
                           usedDS=FALSE)
```
End(Not run)

viewBatch *viewBatch*

Description

Generate image grid of mini-batch of image chips and associated masks created by a DataLoader.

Usage

```
viewBatch(dataLoader, nCols = 3, r = 1, g = 2, b = 3, cNames, cColors)
```
Arguments

Details

The goal of this function is to provide a visual check of a mini-batch of image chips and associated masks generated from a DataLoader.

Value

Image grids of example chips and masks loaded from a mini-batch produced by the DataLoader.

Examples

```
## Not run:
viewBatch(dataLoader=trainDL,
         nCols = 5,
         r = 1,
         g = 2,b = 3,cNames=c("Background", "Mine"),
         cColors=c("gray", "darksalmon"))
```
End(Not run)

viewBatchPreds *viewBatchPreds*

Description

Generate image grid of mini-batch of image chips, masks, and predictions for all samples in a DataLoader mini-batch.

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Usage

```
viewBatchPreds(
  dataLoader,
  model,
  mode = "multiclass",
  nCols = 4,r = 1,
  g = 2,b = 3,cCodes,
  cNames,
  cColors,
  useCUDA = TRUE,
  probs = FALSE,
  usedDS = FALSE
```

```
)
```


Details

The goal of this function is to provide a visual check of predictions for a mini-batch of data.

Value

Image grids of example chips, reference masks, and predictions loaded from a mini-batch provided by the DataLoader.

Examples

```
## Not run:
viewBatchPreds(dataLoader=testDL,
               model=model,
               mode="multiclass",
               nCols =5,
               r = 1,
               g = 2,b = 3,c\text{Codes=c}(1,2),
               cNames=c("Not Mine", "Mine"),
               cColors=c("gray", "darksalmon"),
               useCUDA=TRUE,
               probs=FALSE,
               usedDS=FALSE)
```
End(Not run)

viewChips *viewChips*

Description

Plot a grid of image and/or mask chips

Usage

```
viewChips(
  chpDF,
  folder,
  nSamps = 16,
  mode = "both",
  justPositive = FALSE,
  cCnt = 4,
  rCnt = 4,
  r = 1,
  g = 2,b = 3,
  rescale = FALSE,
```
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```
rescaleVal = 1,
  cNames,
  cColors,
  useSeed = FALSE,
  seed = 42\mathcal{L}
```


Details

This function generates a plot of image chips and/or image masks. It serves as a means to visualize chips generated with the makeChips() or makeChipsMultiClass() function. It can be used as a check to make sure chips were generated as expected.

Value

Plot of image chip grid (if mode = "image"); plot of mask chip grid (if mode ="mask"); plot of image and mask chip grids (if model = "both").

Examples

```
## Not run:
viewChips(chpDF=chpDF,
          folder= "FOLDER CONTAINING CHIPS",
          nSamps = 16,
          mode = "both",
          justPositive = FALSE,
          cCnt = 4,
          rCnt = 4,
          r = 1,
          g = 2,b = 3,
          rescale = FALSE,
          rescaleVal = 1,
          cNames=c("Background",
                   "Building",
                   "Woodland",
                   "Water",
                   "Road"),
          cColor=c("gray",
                   "darksalmon",
                    "forestgreen",
                    "lightblue",
                    "black"),
          useSeed = FALSE,
          seed = 42)
```
End(Not run)

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